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| sudo locale-gen en\_US en\_US.UTF-8  sudo update-locale LC\_ALL=en\_US.UTF-8 LANG=en\_US.UTF-8  export LANG=en\_US.UTF-8  sudo apt update && sudo apt install curl gnupg2 lsb-release  curl http://repo.ros2.org/repos.key | sudo apt-key add -  sudo sh -c 'echo "deb [arch=amd64,arm64] http://packages.ros.org/ros2/ubuntu `lsb\_release -cs` main" > /etc/apt/sources.list.d/ros2-latest.list'  export CHOOSE\_ROS\_DISTRO=crystal  sudo apt update  sudo apt install ros-$CHOOSE\_ROS\_DISTRO-desktop  sudo apt install python3-argcomplete  echo "source /opt/ros/$CHOOSE\_ROS\_DISTRO/setup.bash" >> ~/.bashrc  source /opt/ros/$CHOOSE\_ROS\_DISTRO/setup.bash  ros2 run demo\_nodes\_cpp listener  ros2 run demo\_nodes\_py talker |